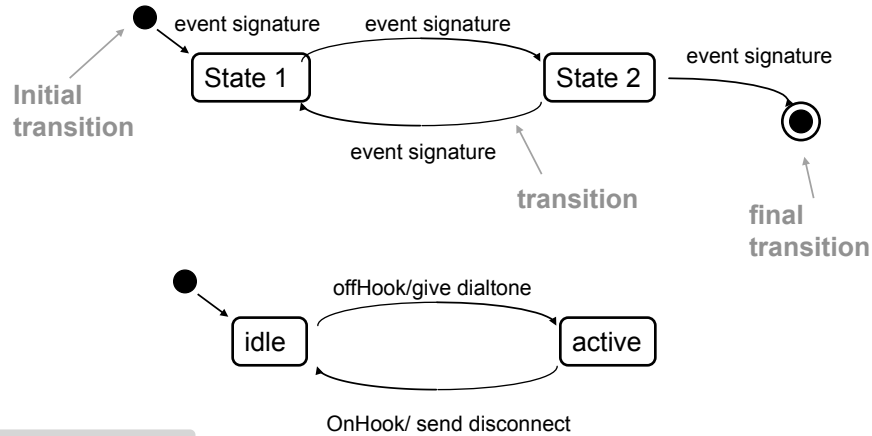


About UML's Statecharts

Finite State Machines

- **Finite State machines (FSMs) describe behavior in terms of states, events, and transitions:**
 - They have their transitions triggered by events.
 - They are equivalently called state (transition) diagrams.
 - They are useful in automating the generation code and tests.
 - Extended FSMs (eFSMs) allow the use of state variables.
 - Douglass has suggested patterns for FSMs of real-time systems
- **For OO Development, an FSM may be developed for each class:**
 - Each object is in exactly one state at any point in time.
 - Events correspond to the messages sent by other objects.
 - Many classes do not have sophisticated state behavior - often just one state.
 - Contrary to Structural Programming, we do not develop an FSM for the system: behavior is distributed across objects:
 - » semantically we can think of communicating eFSMs

Basic UML Notation for State Machine

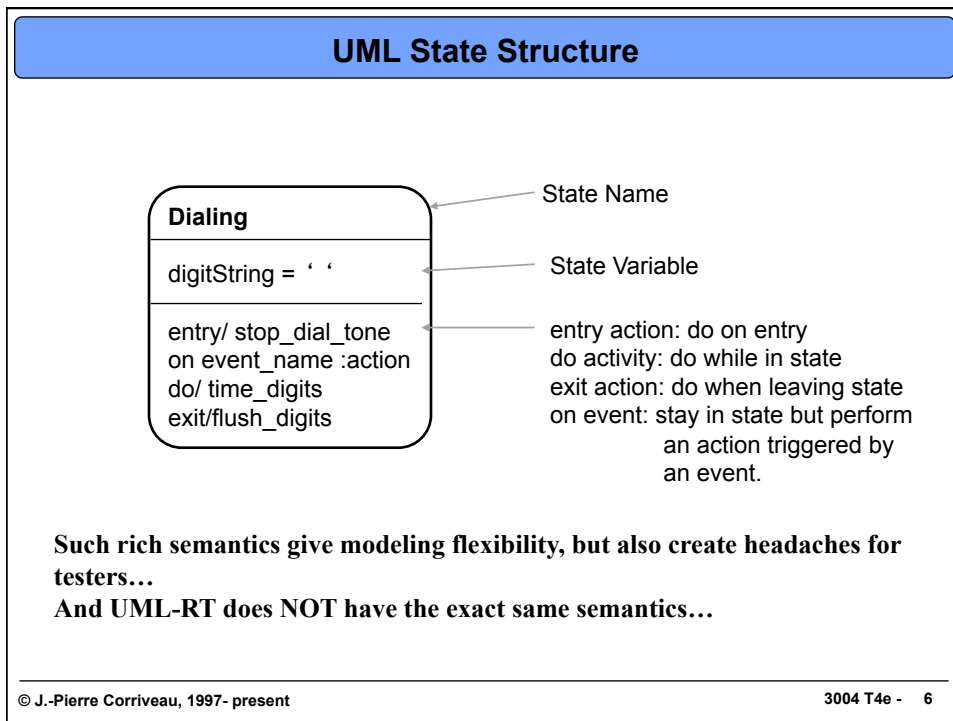
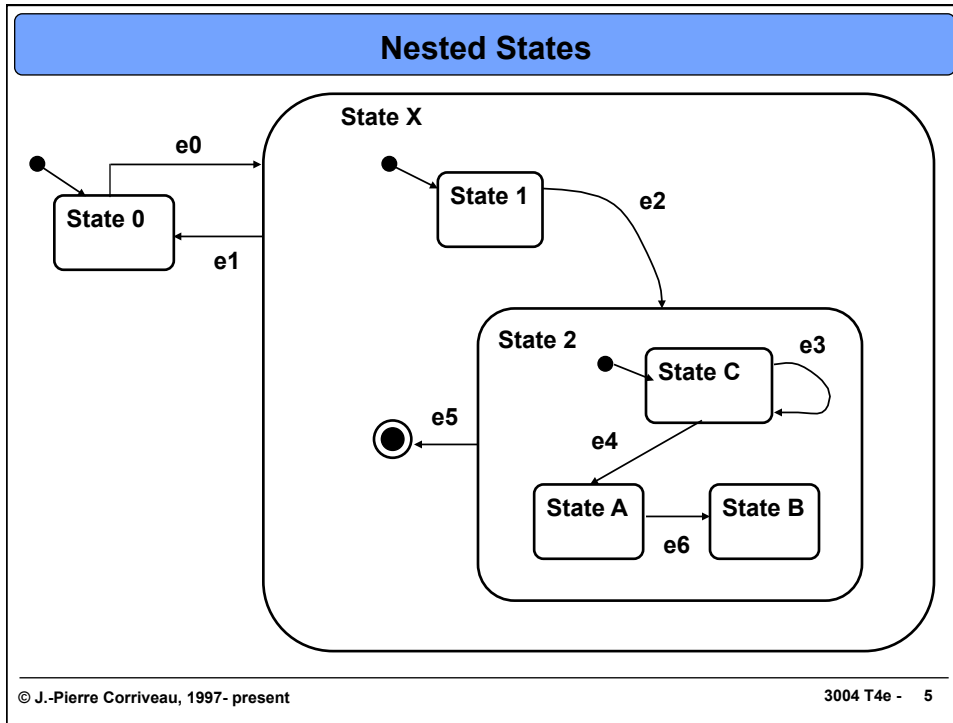


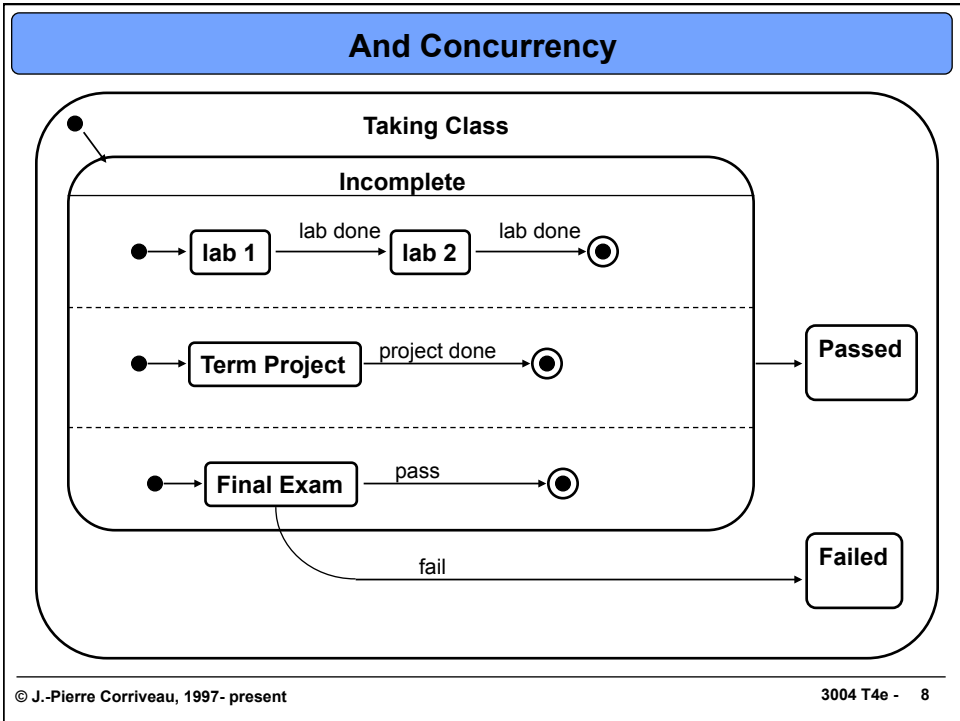
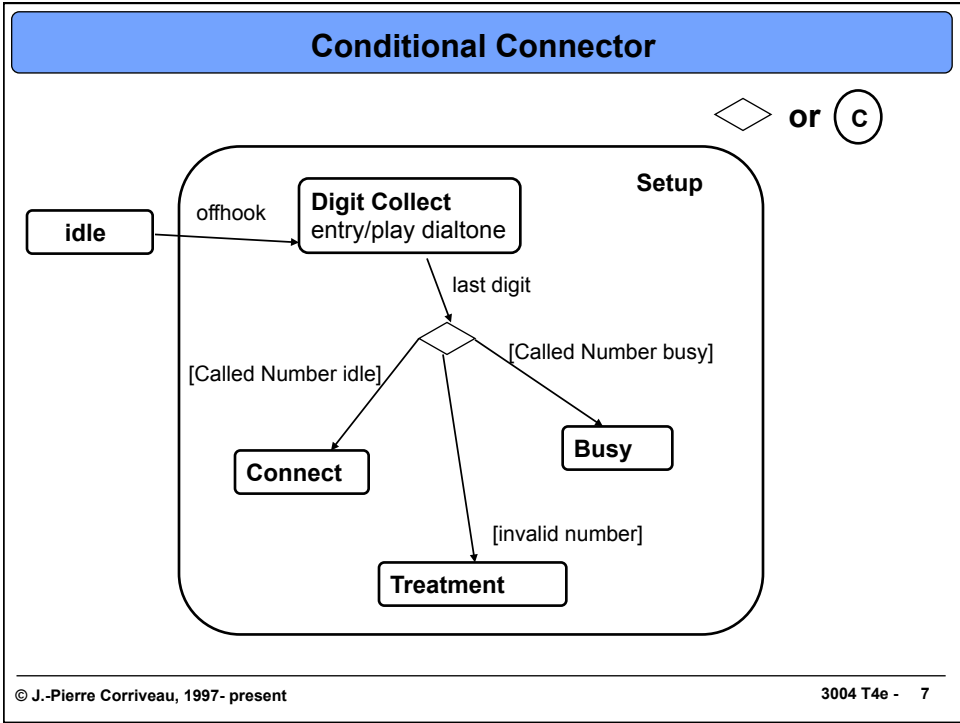
Event signature:

event(parameters: type) [guard condition] / action ^sends

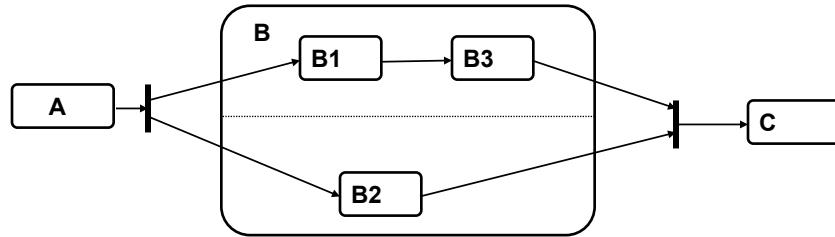
Statecharts = Hierarchical eFSMs

- **The notation used in UML is taken almost directly from Harel Statecharts:**
 - Statecharts embellish traditional state machines by providing notation for nesting and concurrency.
 - The embellishments help simplify visually state machines, which can, otherwise, become quite complex.
 - » But the embellishments introduce semantic difficulties...
- **Hierarchical eFSMs lend themselves to iterative development: (the usual stub idea...)**
 - but remember that a single transition may make an FSM non-deterministic!
 - and non-determinism is not the only problem of communicating state machines: deadlocks and livelocks must be detected...
 - and Binder insists on statecharts being flattened if tests are to be extracted from them...

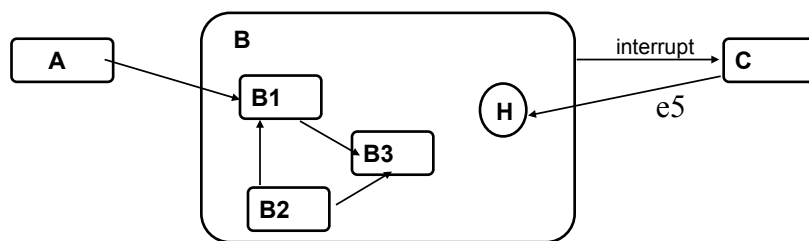




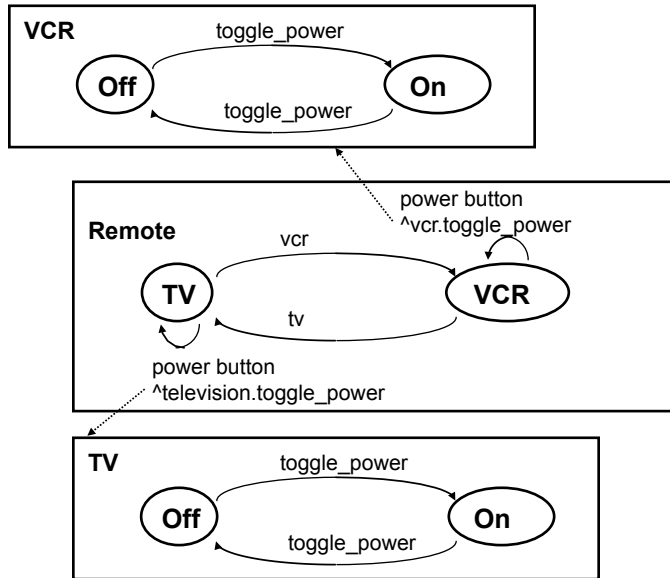
Explicit Fork and Join



History Indicator



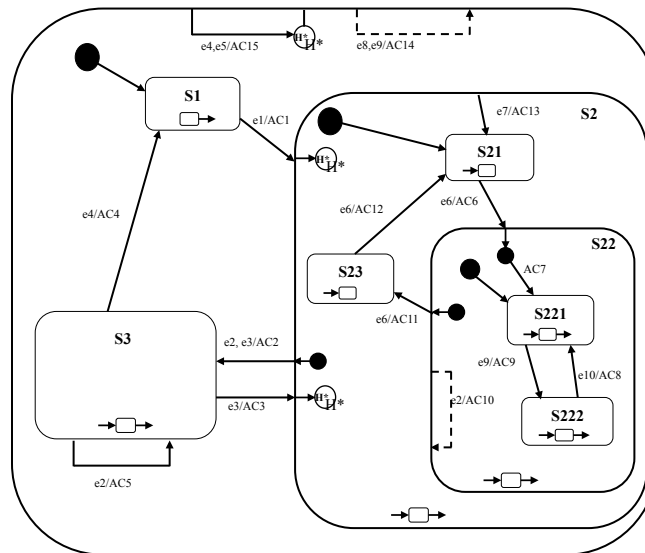
Sending Events to Other Objects



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Understanding Hierarchical State Machines in ROSE-RT



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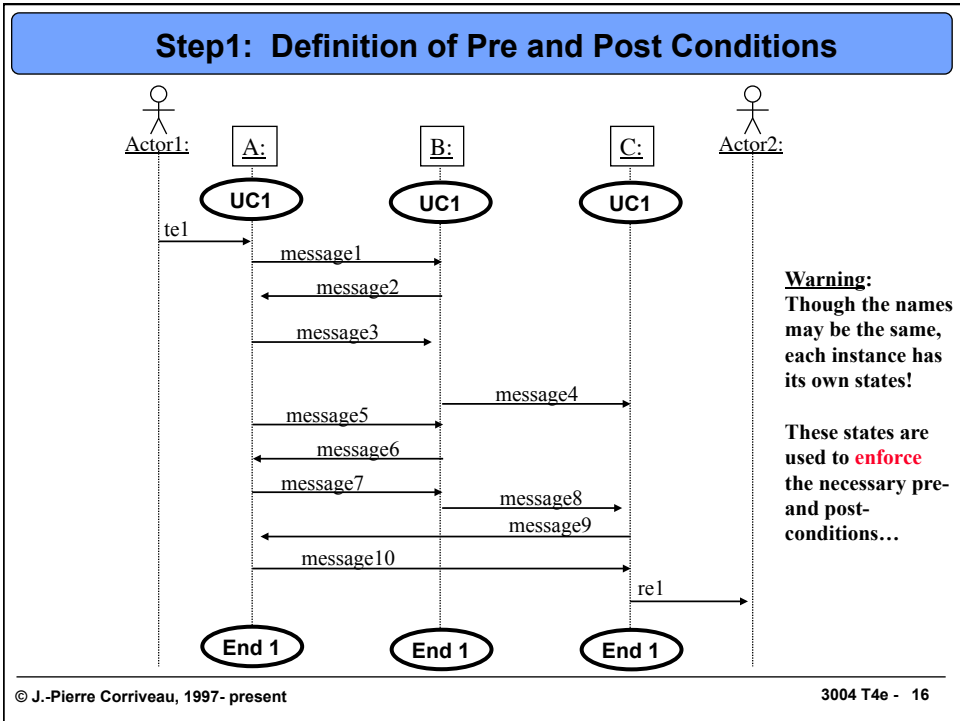
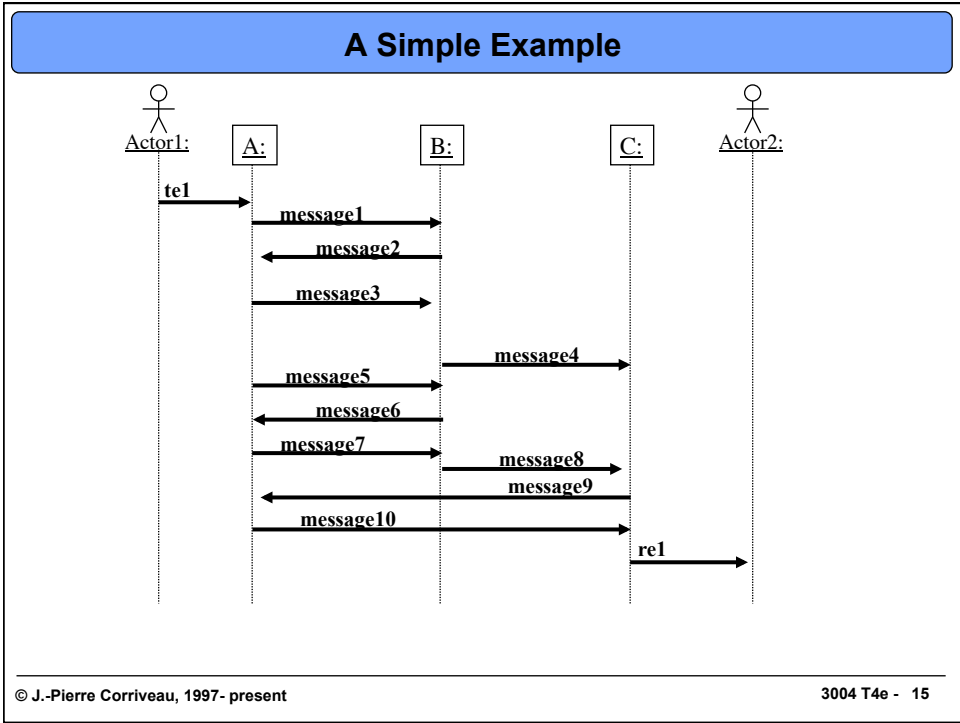
From Problem Statement To Statecharts

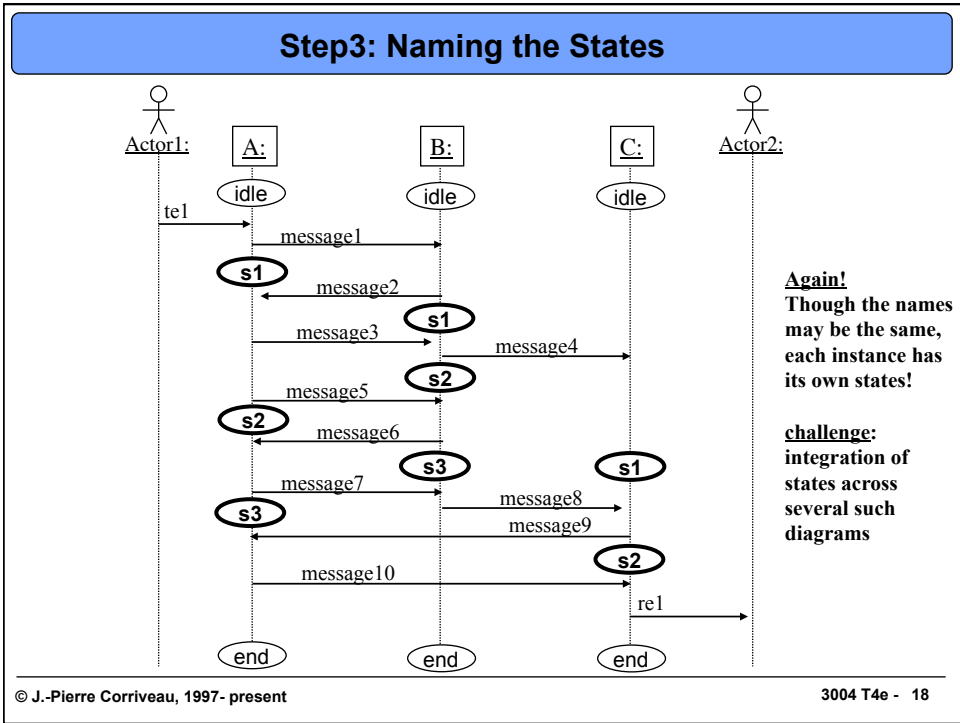
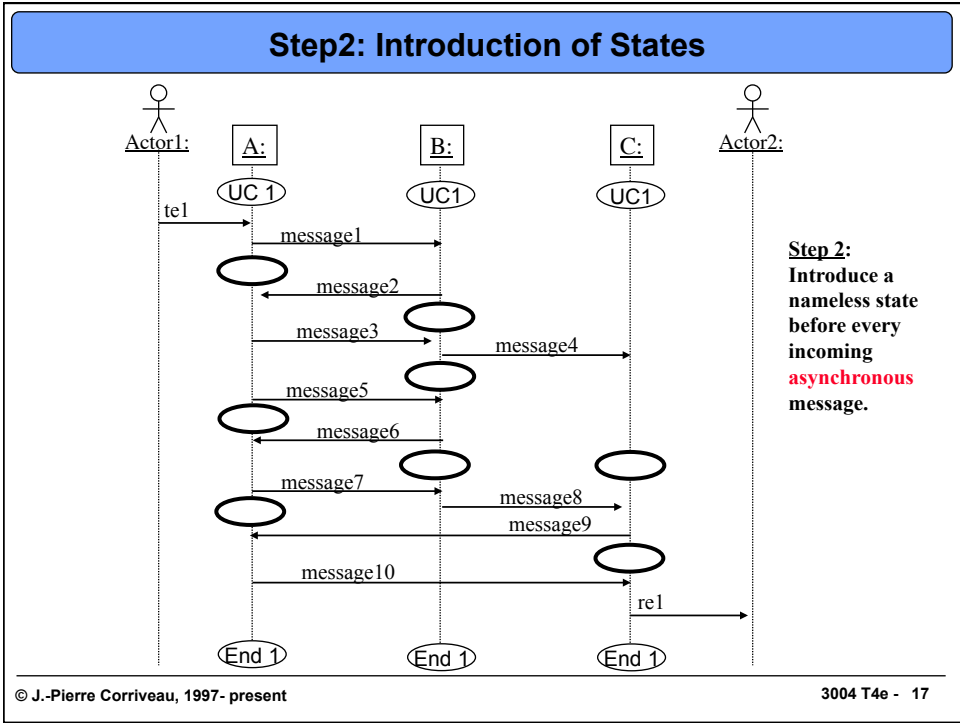
The Scenario-Driven Recipe

In UML the transition from a set of UCs to a set of a sequences of messages and to the relevant statecharts can be conducted in 4 steps:

1. Definition of pre and post conditions associated with **a** use case
2. In each instance of the *corresponding* interaction diagram, introduction of states before every incoming message
3. Naming of the states
4. Generation of statecharts

A glitch: this recipe downplays completely inter-UC relationships...





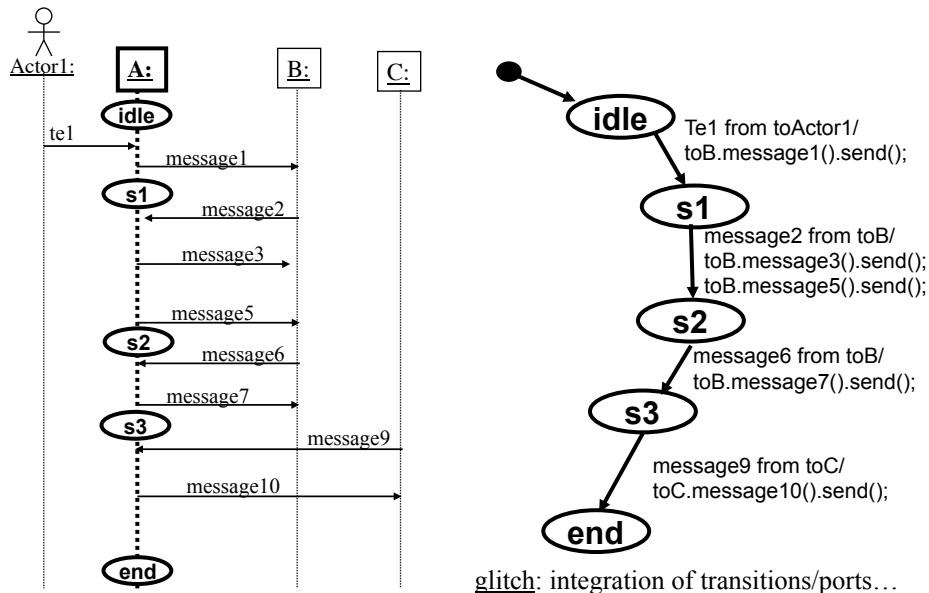
Step4: Generation of Statecharts

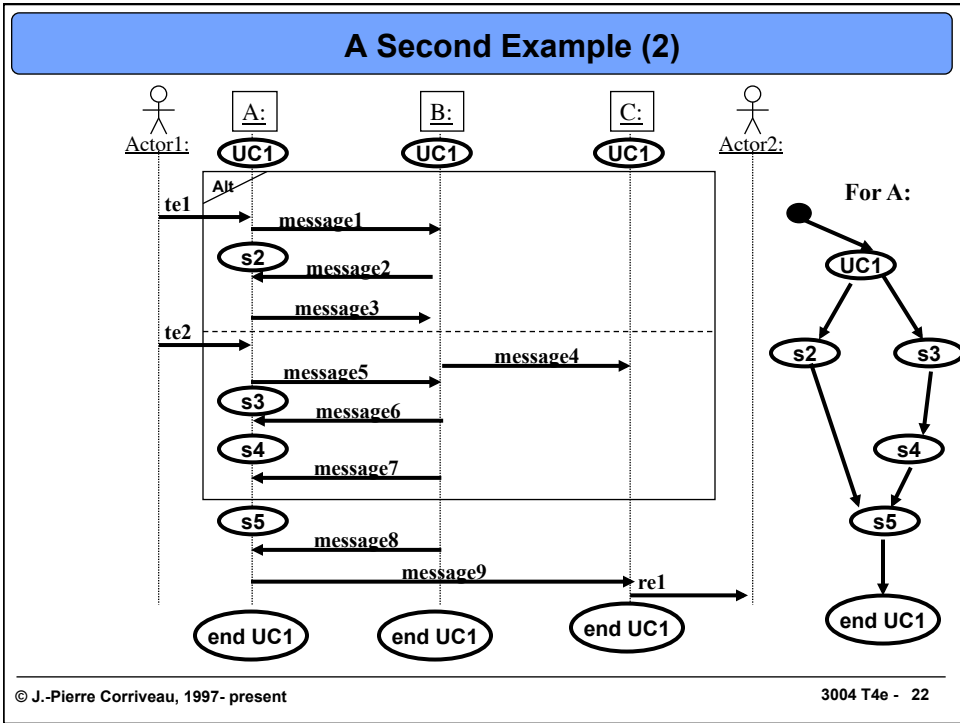
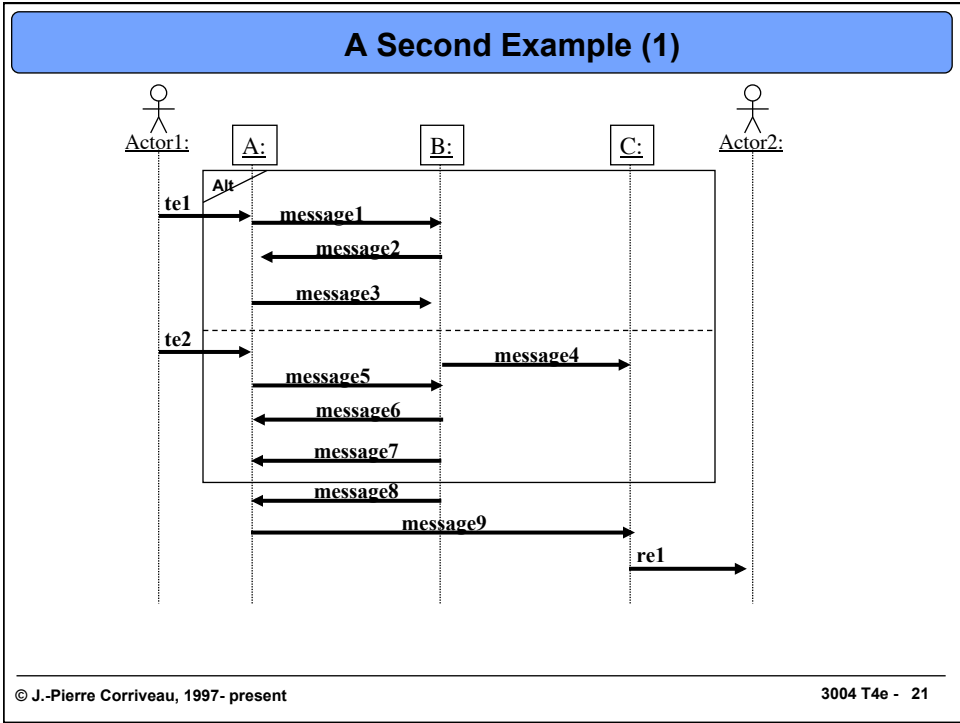
Task:

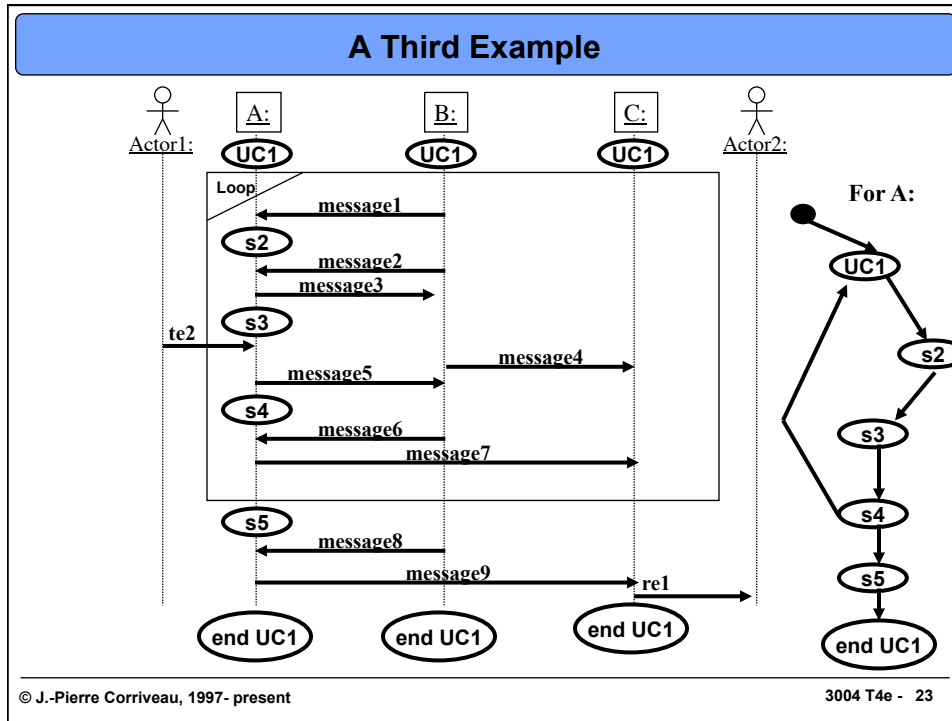
For each instance of the sequence define a statechart as follows:

- Define a state for each state defined in the sequence diagram
- Define transitions between the states
- Define each transition in terms of a triggering event (i.e., an incoming message) and transition actions (i.e., sending outgoing messages)

Step4: Generation of Statecharts







Looks Simple?

- **The ultimate success of the extraction of a role state machine depends:**
 - on the exact semantics of the notation you use.
 - » UML's statecharts are one of several possible semantics.
 - » Other models exist: eg., Douglass
 - on the complexity of the interaction diagram to start with:
 - » UML 2.0 sequence diagrams have much more complicated syntax and semantics than the interaction diagrams currently in ROSE-RT. This does complicate role state machine extraction.
- **Role state machines??**
 - We obtain a state machine for each instance participating in a single use case.
 - Other instances of the same class may participate in other use cases!
 - » We will say that instances of a class may play different *roles* in different use cases.
 - » Once we have role state machines, we will need to *consolidate* them (to use Goma's terminology).

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